



НОЦ "ПАРАЛЛЕЛЬНЫЕ ВЫЧИСЛЕНИЯ"  
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September 6

# Beam dynamics calculation

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<http://parallel-compute.com>



# Outline

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- **Problem formulation**
- **Numerical methods**
- **OpenMP and CUDA realization**
- **Results**

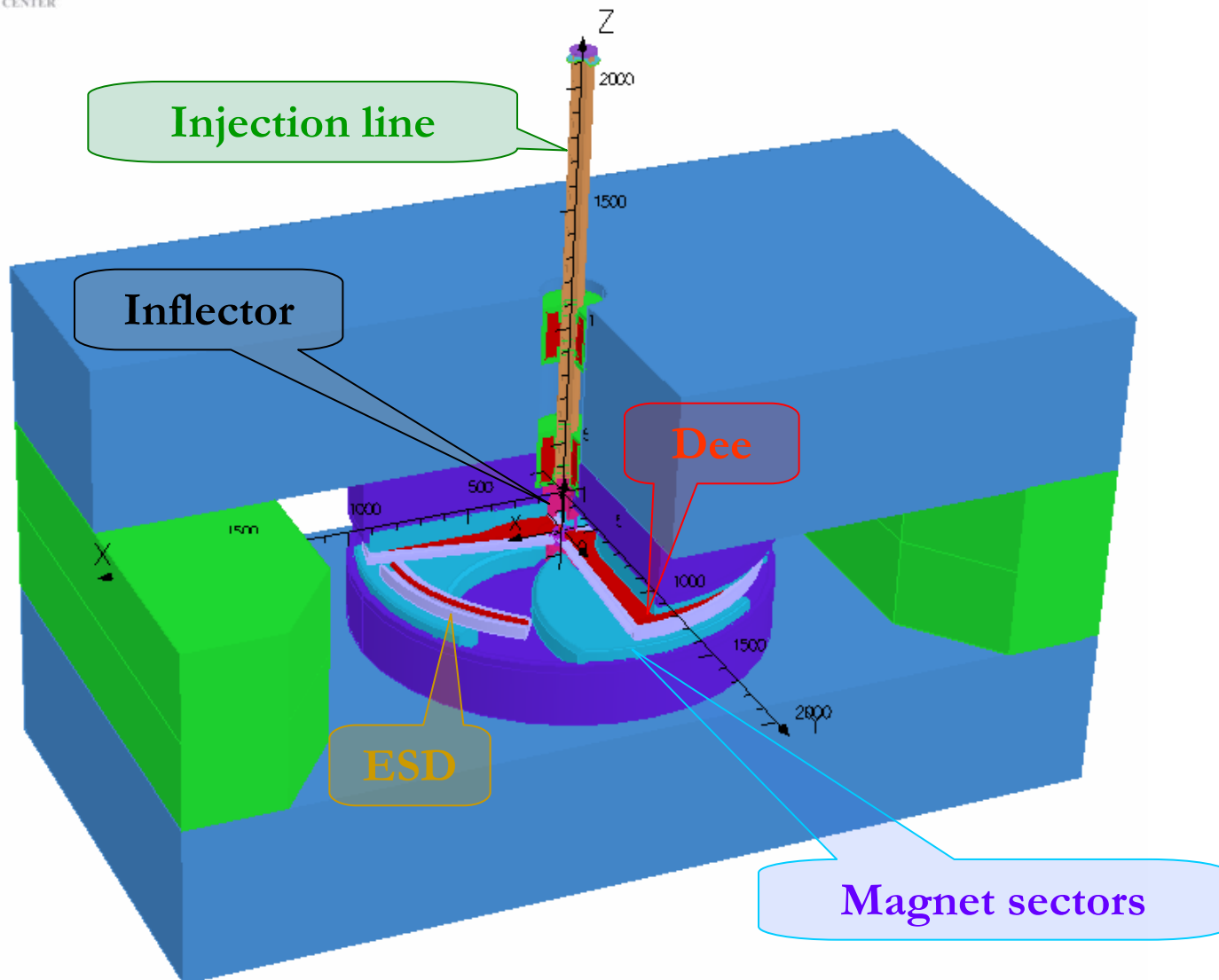
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**CBDA: Cyclotron Beam Dynamic Analysis code**



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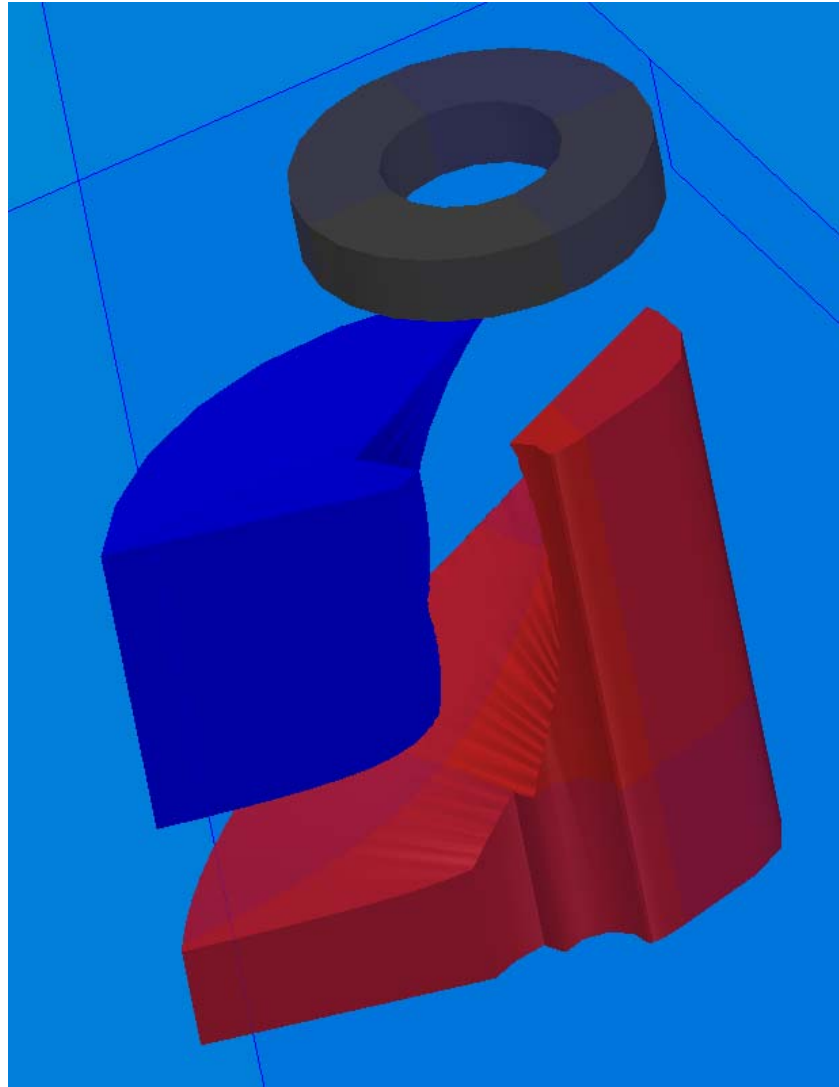
# Computer model of the cyclotron





# Inflector

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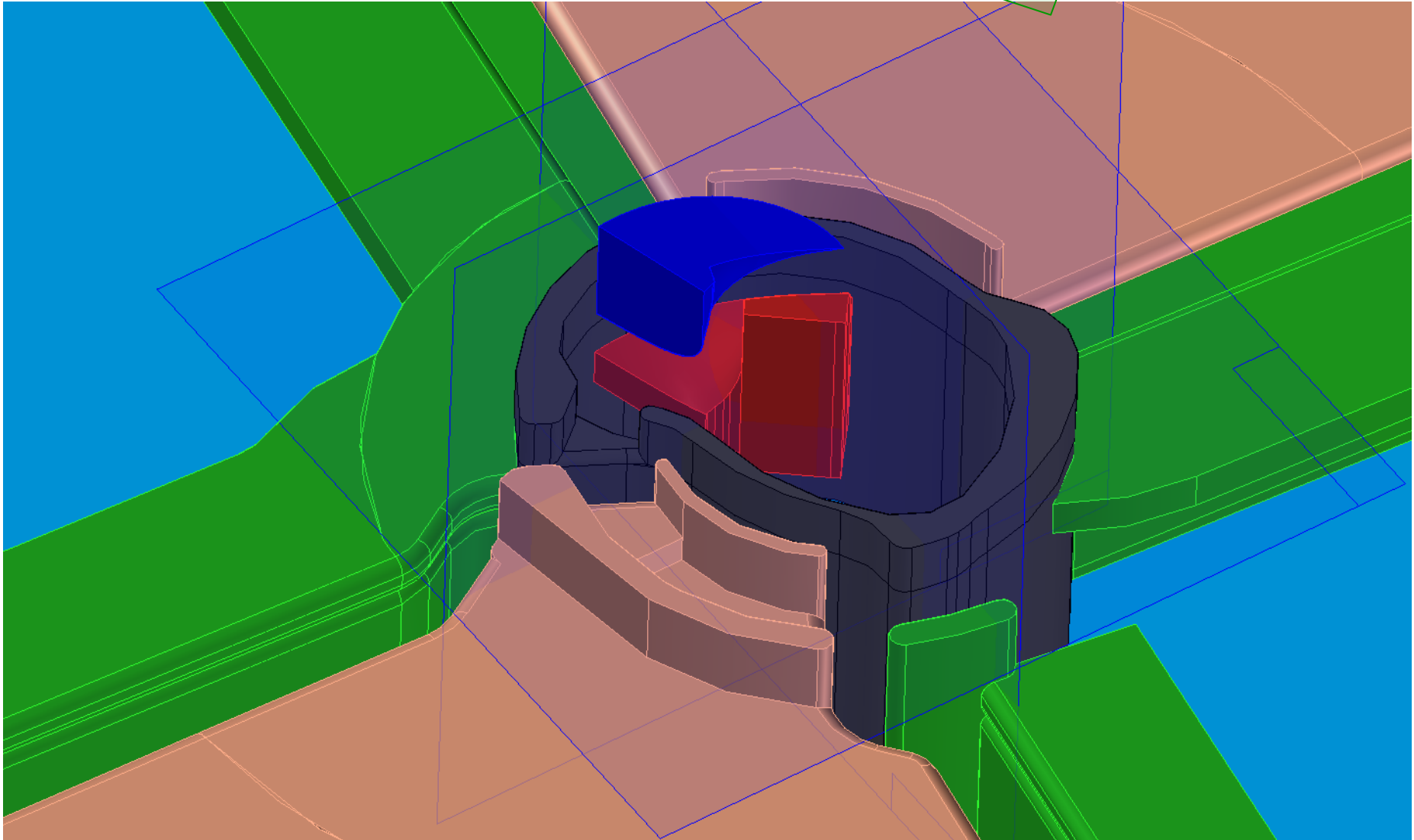




# Central region

Courtesy A.S. Vorozhtsov

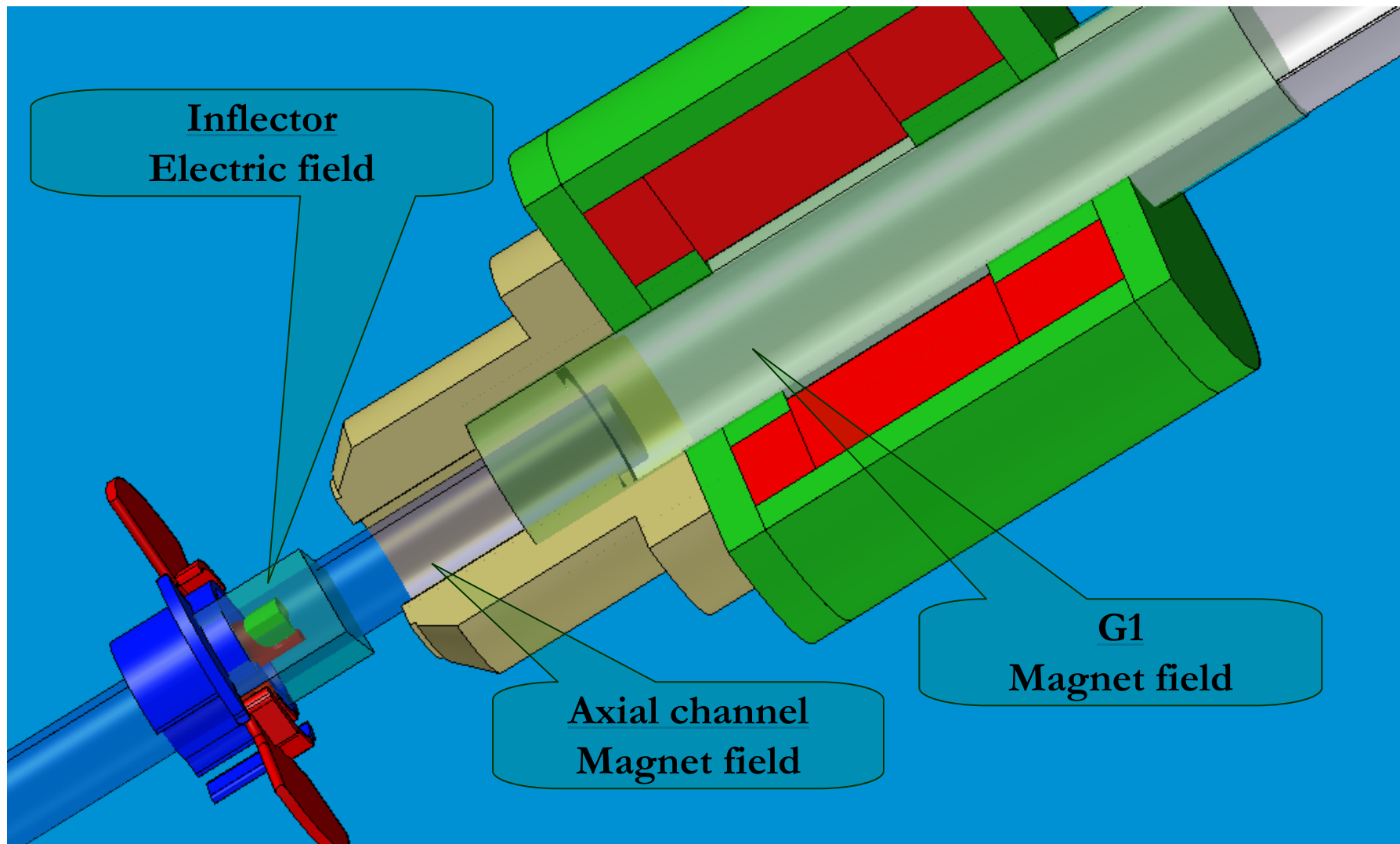
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# Regions of the field maps

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# Motion equation

$$(\vec{r}_i, \vec{p}_i, t), \quad i = 1 \dots N$$

$$\frac{d}{dt} \vec{p}_i = \vec{F}_i, \quad i = 1 \dots N$$

$$\left\{ \begin{array}{l} m_i \frac{d}{dt} (\gamma_i \vec{v}_i) = q_i \left( \vec{E}_{ext}(\vec{r}_i, t) + \vec{E}_s(\vec{r}_i, t) + [\vec{v}_i, \vec{B}_{ext}(\vec{r}_i)] \right) \\ \gamma_i = 1 / \sqrt{1 - \beta_i^2}, \quad \beta_i = \frac{v_i}{c} \\ \vec{r}_i|_{t=t_i} = \vec{r}_i^{(0)}, \quad \vec{v}_i|_{t=t_i} = \vec{v}_i^{(0)}, \quad \text{или} \quad \vec{r}_i|_{t=0} = \vec{r}_i^{(0)}, \quad \vec{v}_i|_{t=0} = \vec{v}_i^{(0)} \\ 1 \leq i \leq N, \quad \vec{r}_i \in V \end{array} \right.$$



# Space charge effect

$$\begin{aligned} \operatorname{div} \vec{E}_s &= \frac{\rho}{\varepsilon_0}, & \operatorname{rot} \vec{B}_s &= \mu_0 \vec{J}_s + \frac{1}{c^2} \frac{\partial}{\partial t} \vec{E}_s \\ \operatorname{rot} \vec{E}_s &= -\frac{\partial}{\partial t} \vec{B}_s, & \operatorname{div} \vec{B}_s &= 0, \quad \frac{1}{\mu_0 \varepsilon_0} = c^2 \end{aligned}$$

## PIC methods

$$\vec{E}_s = -\nabla \varphi$$

$$\begin{cases} \Delta \varphi(p) = -\frac{\rho(p)}{\varepsilon_0}, & p \in \Omega \\ \varphi|_{\Gamma_D} = \varphi_D, \quad \frac{\partial \varphi}{\partial n}|_{\Gamma_N} = \psi_N, & \Gamma_D \cup \Gamma_N = \Gamma \end{cases}$$

## PP methods

$$\begin{aligned} \vec{E}_s(\vec{r}_i) &= \frac{1}{4\pi\varepsilon_0} \sum_{j \neq i}^N \frac{q_j}{|\vec{r}_i - \vec{r}_j|^3} (\vec{r}_i - \vec{r}_j), \quad i = 1 \dots N \\ \vec{E}_s(j \rightarrow i) &= \frac{1}{4\pi\varepsilon_0} \frac{q_j}{R^3} (\vec{r}_i - \vec{r}_j), \quad |\vec{r}_i - \vec{r}_j| < R \end{aligned}$$





# Space charge effect

$$\begin{cases} \Delta\varphi(p) = -\frac{\rho(p)}{\varepsilon_0}, & p \in \Omega \\ \varphi|_{\Gamma} = 0 \end{cases}$$

FFT use for Fourier set

$\rho(x_i, y_j, z_s)$  – obtain from the particle distribution

$$\bar{\rho}(n, m, k) = \frac{8}{N_x N_y N_z} \sum_{s=1}^{N_z-1} \sum_{j=1}^{N_y-1} \sum_{i=1}^{N_x-1} \rho(x_i, y_j, z_s) \sin\left(\frac{\pi ni}{N_x}\right) \sin\left(\frac{\pi mj}{N_y}\right) \sin\left(\frac{\pi ks}{N_z}\right)$$

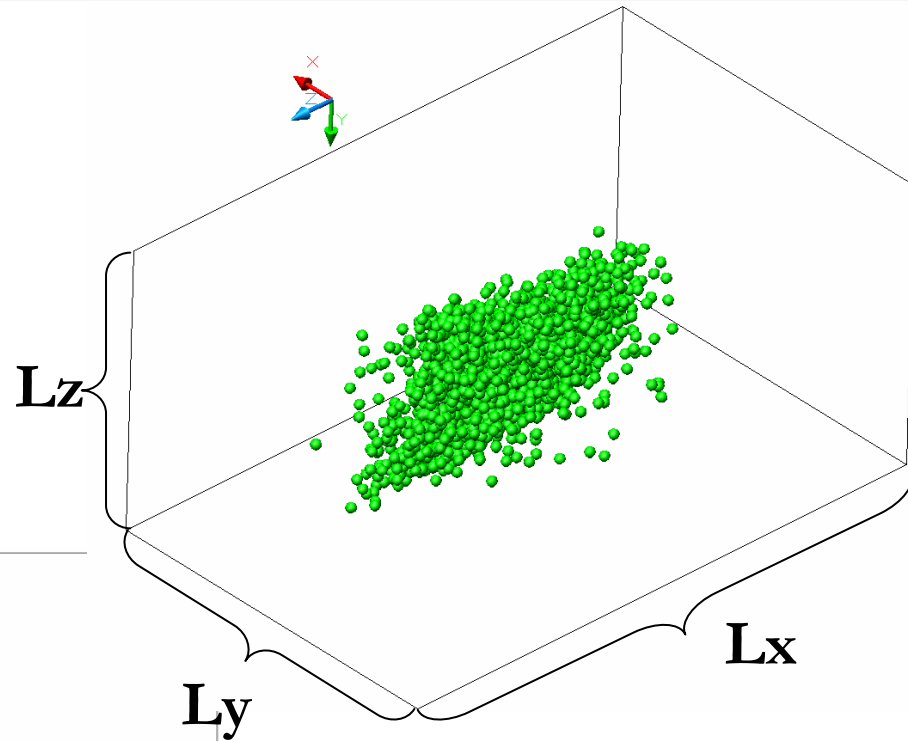
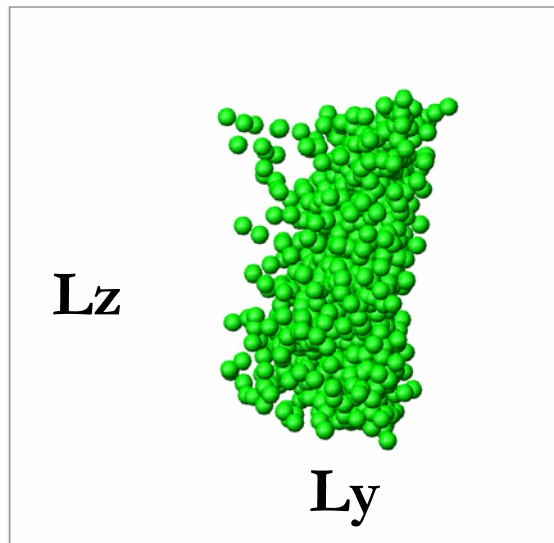
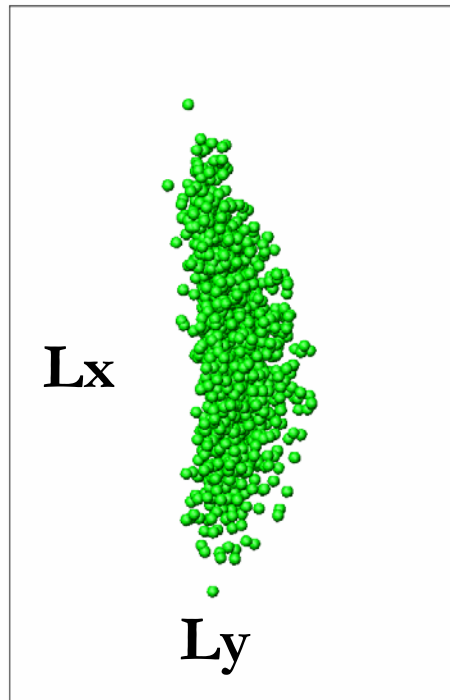
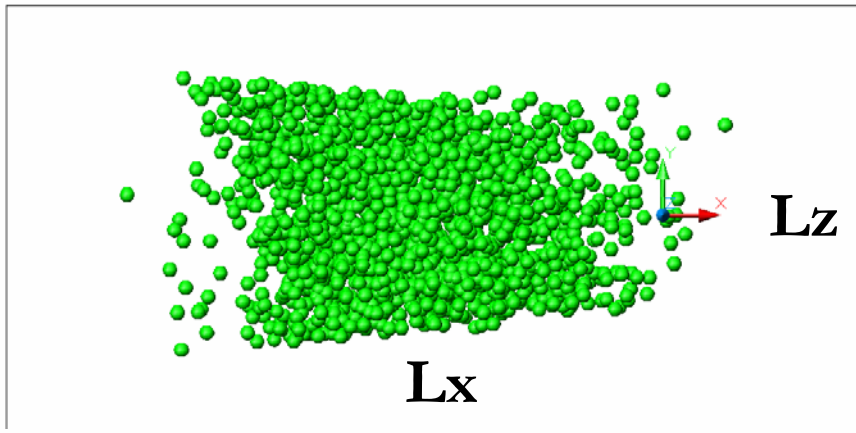
$$\bar{\varphi}(n, m, k) = -\bar{\rho}(n, m, k) \left[ \left(\frac{\pi n}{L_x}\right)^2 + \left(\frac{\pi m}{L_y}\right)^2 + \left(\frac{\pi k}{L_z}\right)^2 \right]^{-1}$$

$$\varphi(x_i, y_j, z_s) = \sum_{k=1}^{N_z-1} \sum_{m=1}^{N_y-1} \sum_{n=1}^{N_x-1} \bar{\varphi}(n, m, k) \sin\left(\frac{\pi ni}{N_x}\right) \sin\left(\frac{\pi mj}{N_y}\right) \sin\left(\frac{\pi ks}{N_z}\right)$$



# Bunch area

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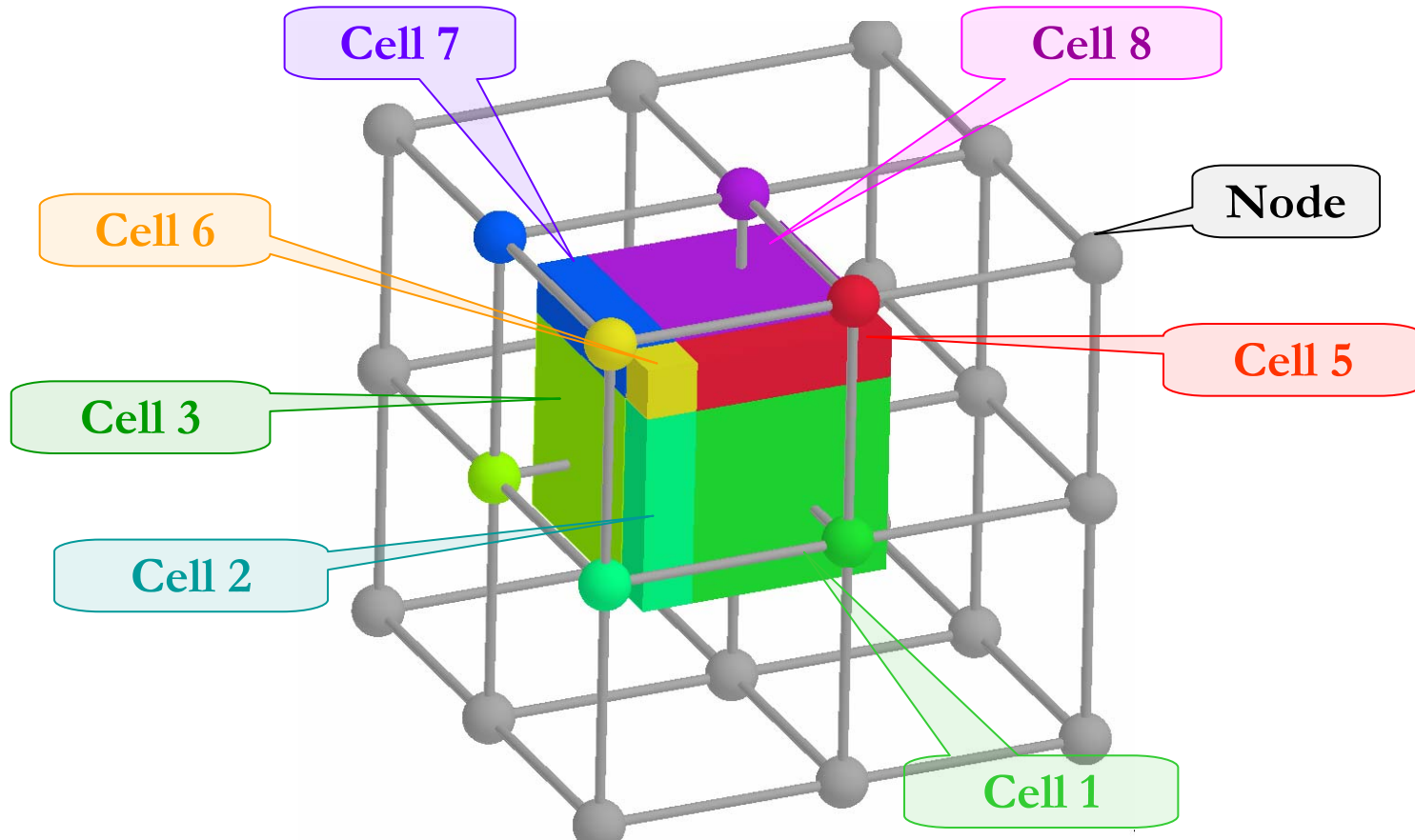


Mesh  $Nx \cdot Ny \cdot Nz$

Mesh steps  $hx = \frac{Lx}{Nx}, hy = \frac{Ly}{Ny}, hz = \frac{Lz}{Nz}$



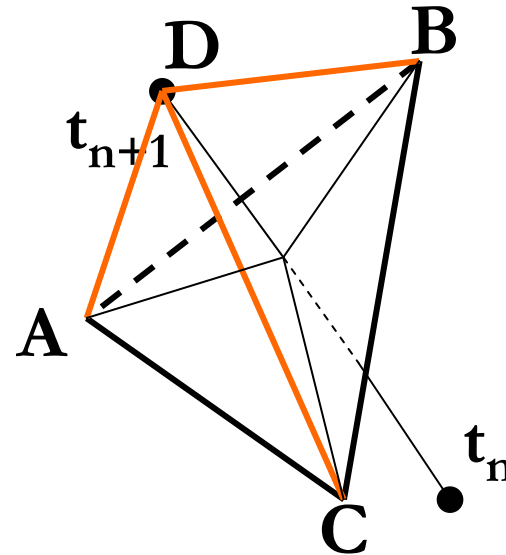
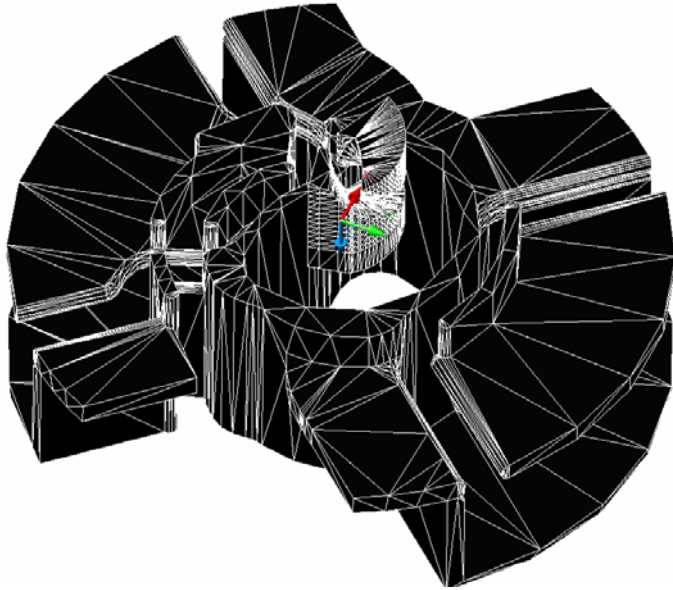
# Charge density calculation





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# Particle losses



If point D belongs the  $ABC$  triangle then

$$S_{\Delta ADC} + S_{\Delta ADB} + S_{\Delta CDB} = S_{\Delta ABC}$$

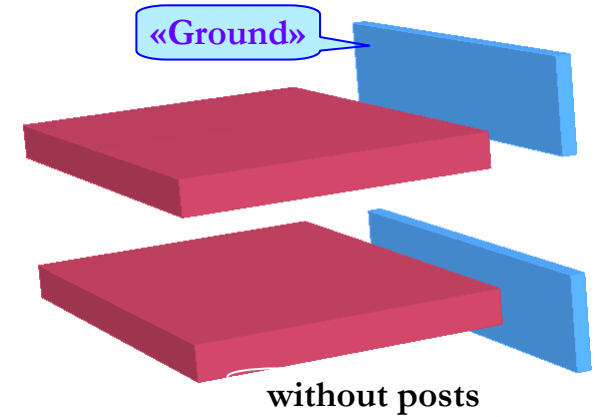
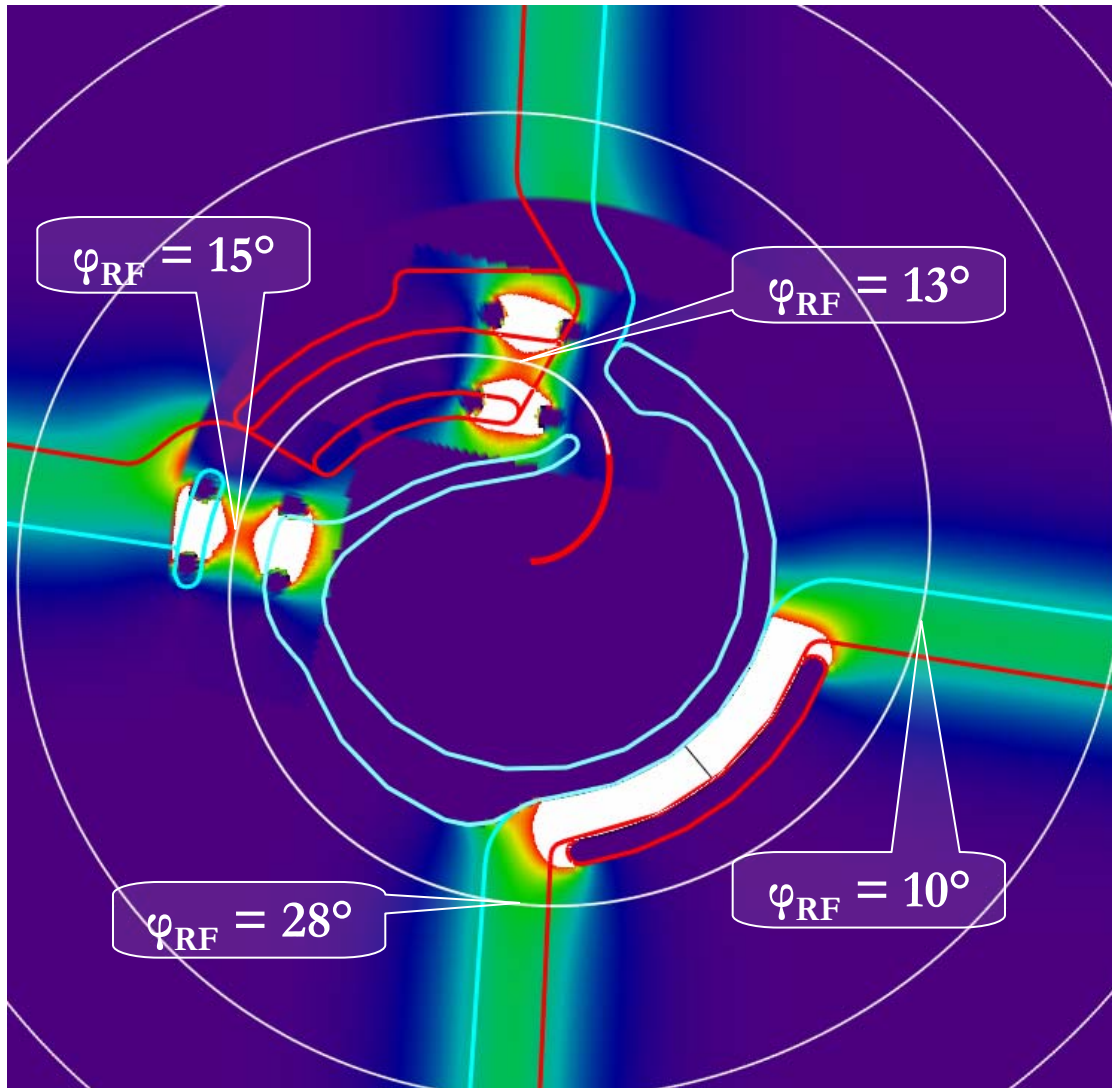
**Cross condition**  $S_{\Delta ADC} + S_{\Delta ADB} + S_{\Delta CDB} < S_{\Delta ABC} + \varepsilon_{\Delta}$

where  $\varepsilon_{\Delta}$  – maximal deviation from surface

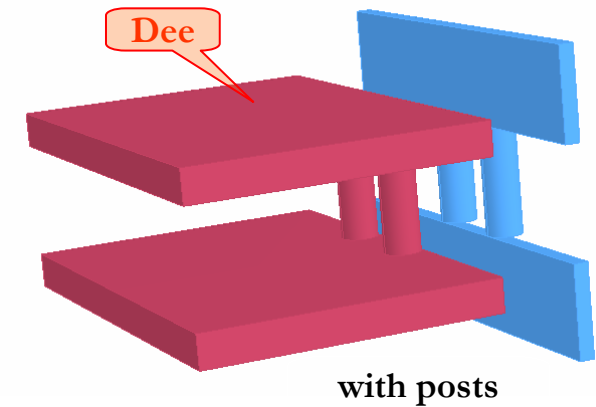


# Central region optimization

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$$F = ZU_{RF} - W_{GAP}$$





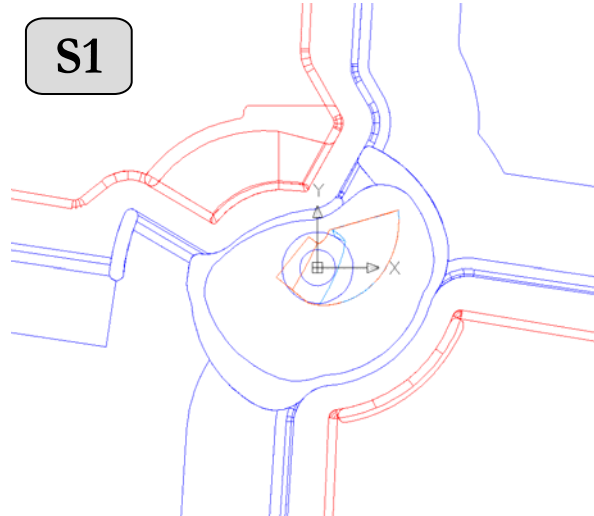
# Choice optimal configuration

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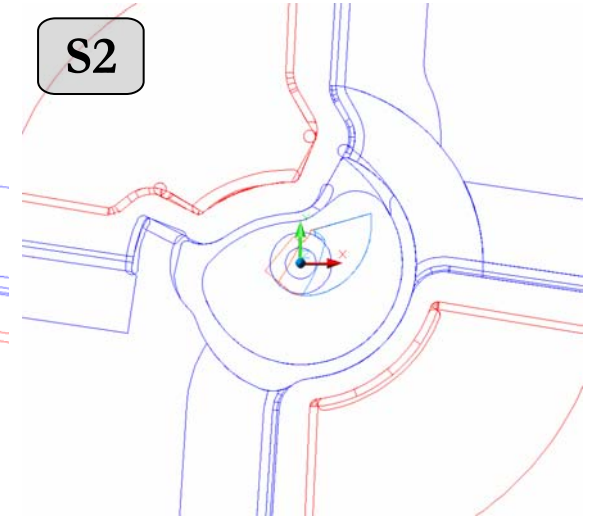
S0



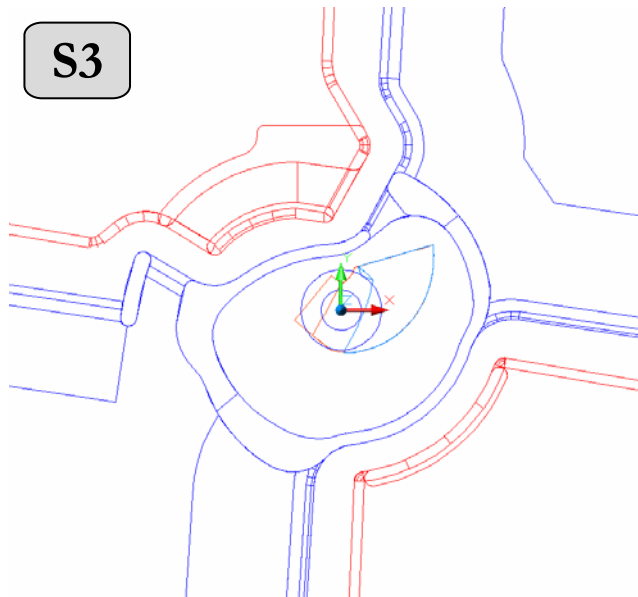
S1



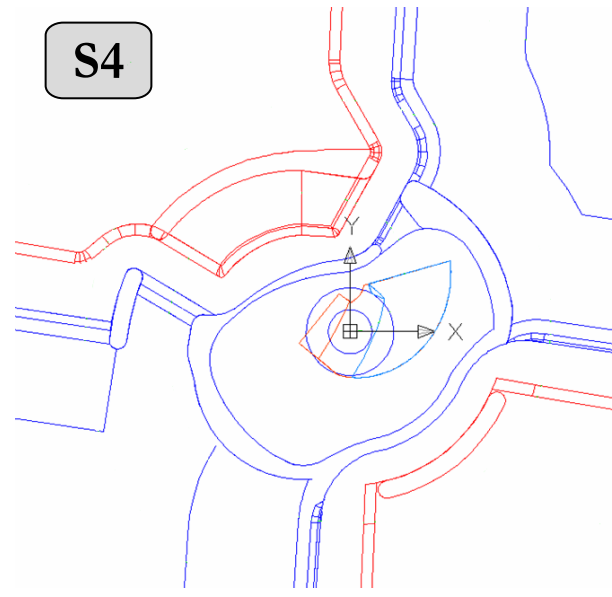
S2



S3



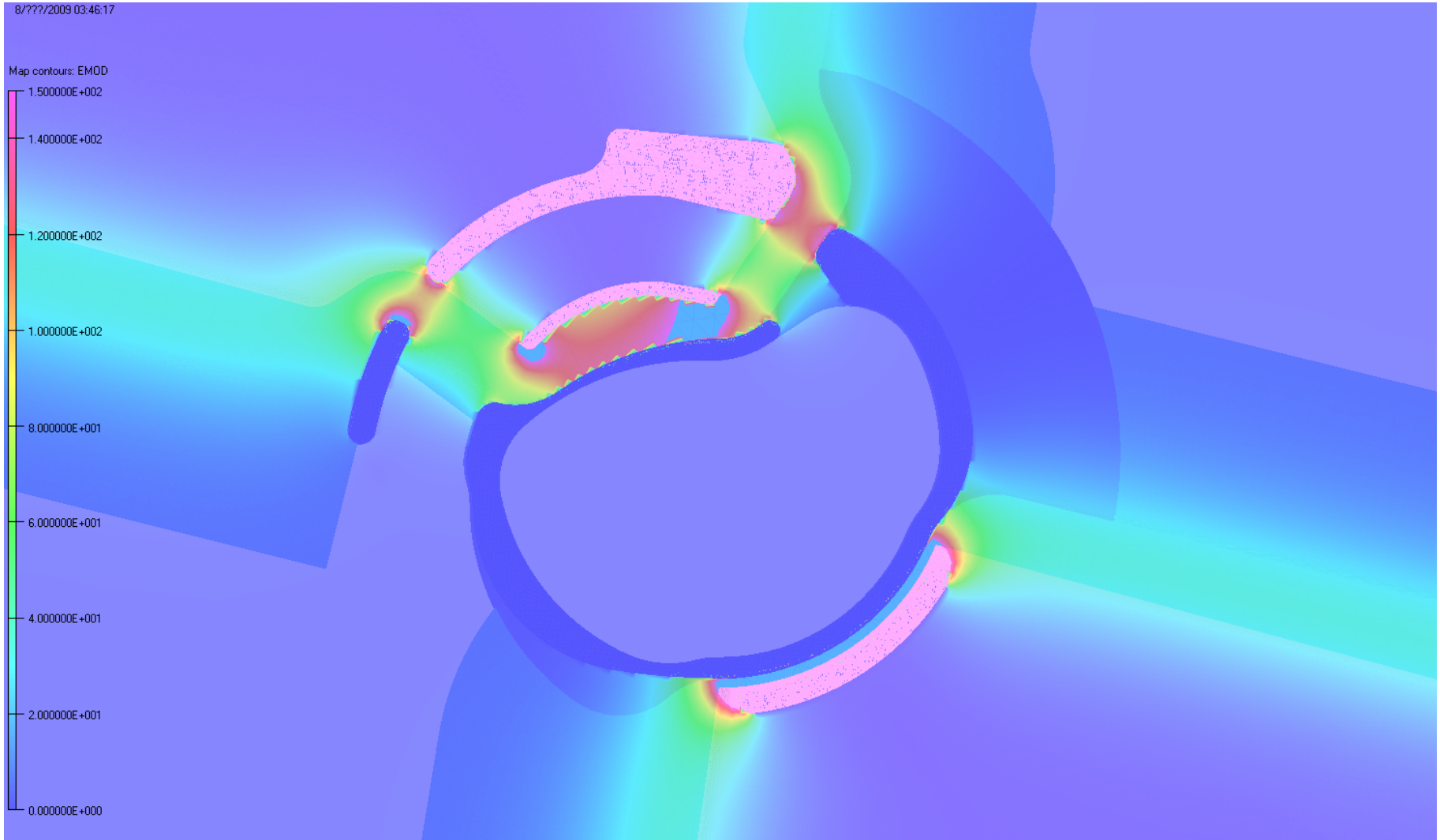
S4





# Accelerating field distribution

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# Very time consuming problem

- About 5 different variants - minimum
- Many ions species - accelerated
- Very complicated structure
- Multi macro particle simulation for SC dominated beams



**One run requires ~  
several days of computer time**





# Numerical methods

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- **Runge-Kutta 4<sup>th</sup> order**
  - ( motion equations )
- **FFT for Poisson equation**
  - ( space charge effect )
- **Beam losses**
  - ( «ray tracing» algorithm )



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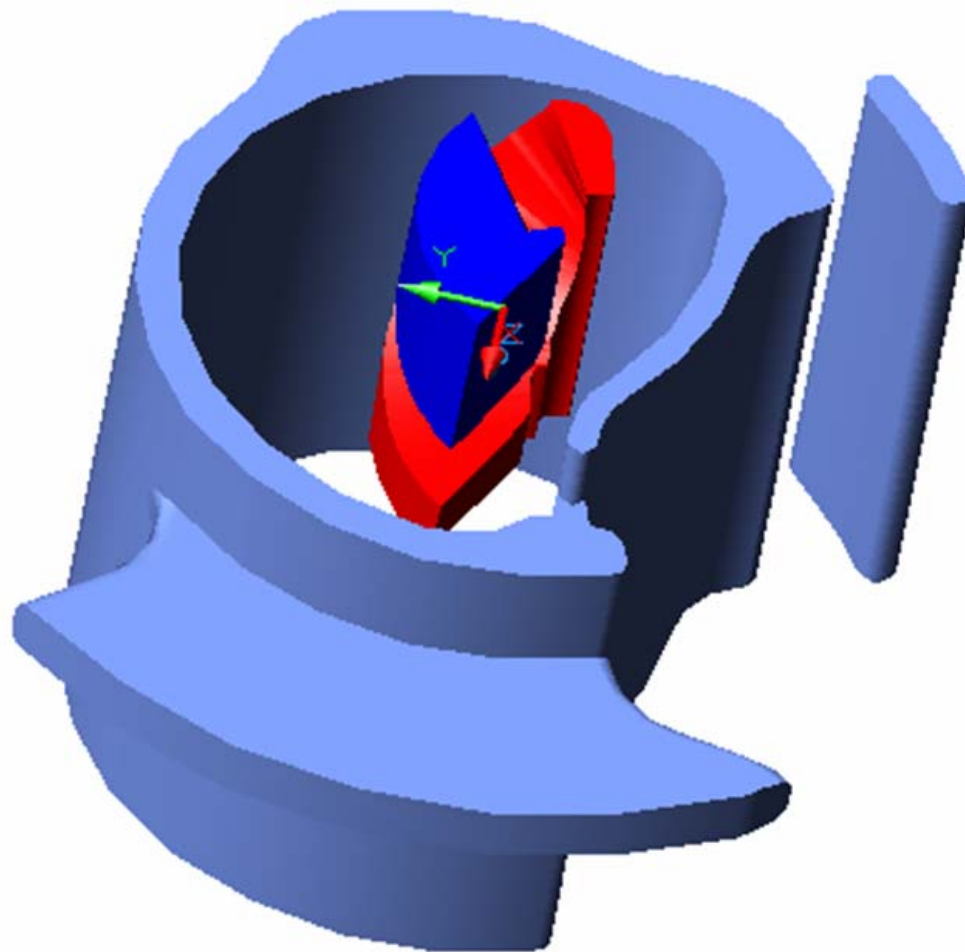
# Open Multi-Processing

## OpenMP



# Spiral inflector

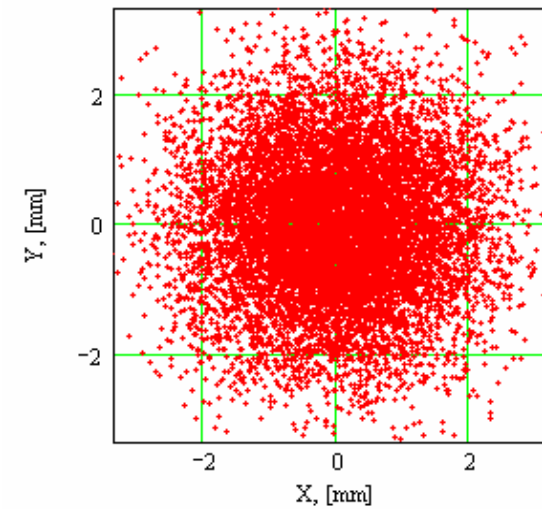
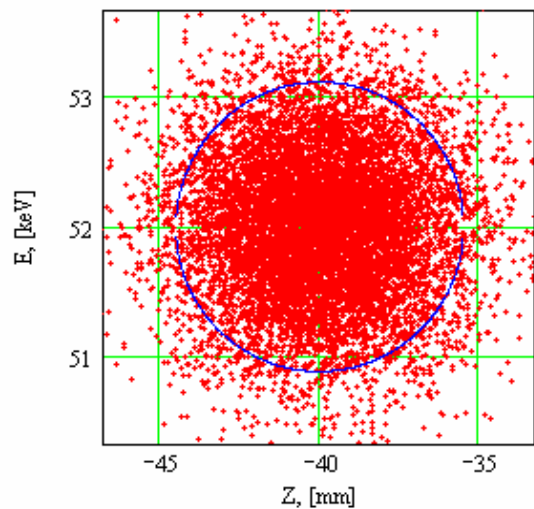
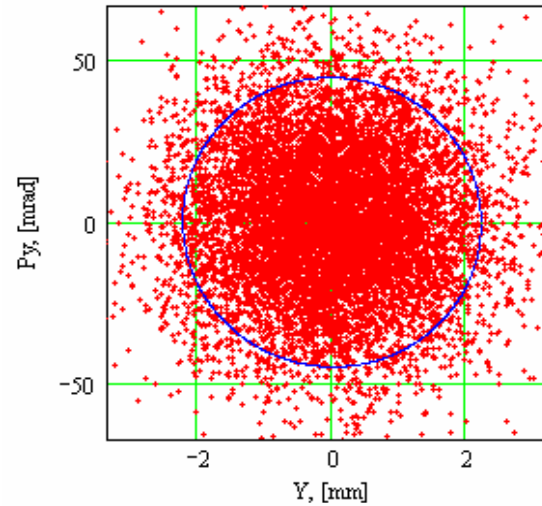
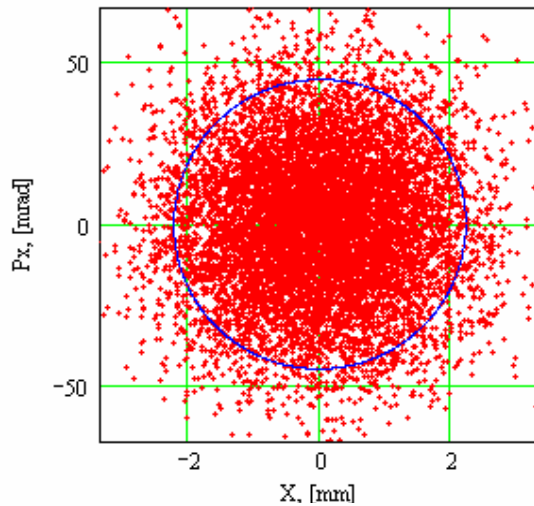
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# Beam parameters at the inflector entrance

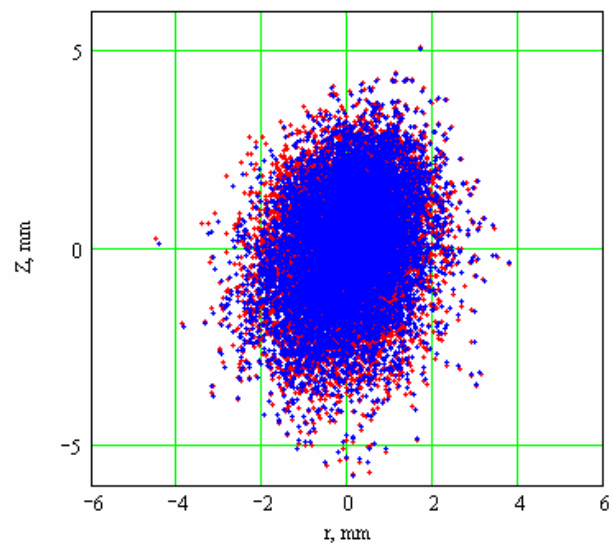
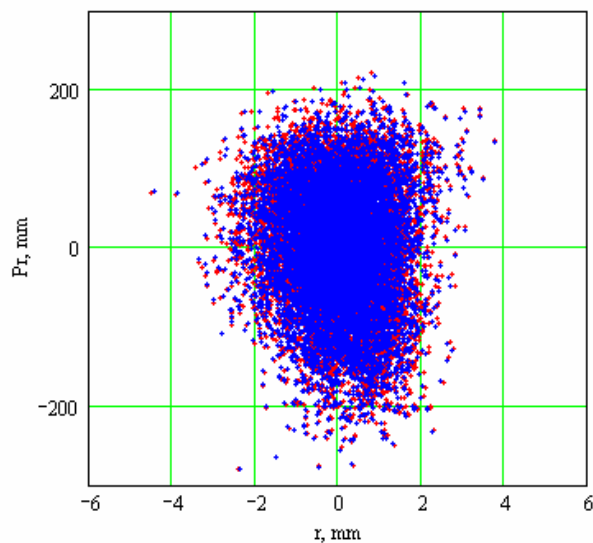
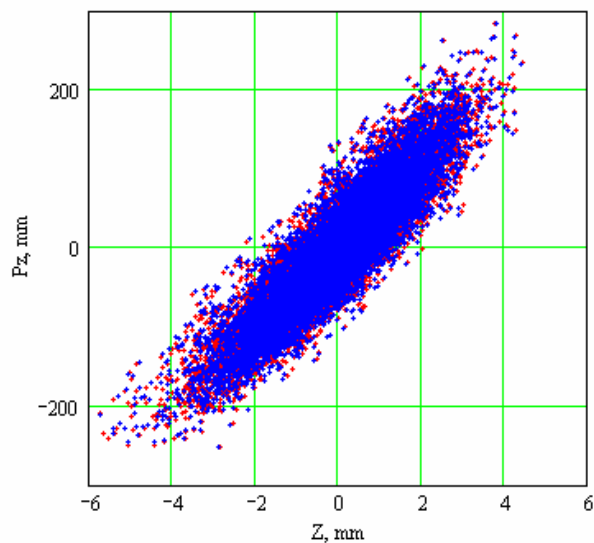
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# Beam parameters at the inflector exit



Blue points – PIC by FFT ( mesh:  $2^5 \times 2^5 \times 2^5$  )

Red points – PP



# Calculation time

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Method	Without OpenMP	With OpenMP	Computer platform
<b>PP</b>	4 h. 53 min.	2 h. 34 min.	AMD Turion 64×2, 1.60 GHz
	4 h. 38min	1 h. 25 min.	Intel Core2 Quad 2.4 GHz
<b>PIC</b> $2^5 \times 2^5 \times 2^5$	~11 min.	~6 min.	AMD Turion 64×2, 1.60 GHz
	7 min.	~2 min.	Intel Core2 Quad 2.4 GHz

10,000 particles

No geometry losses



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# CUDA

Compute Unified Device Architecture



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# CUDA kernel-functions

- **Track** ( field maps, particle coordinate and velocity )
- **Losses** (setup geometry, particle coordinate )
- **Rho** ( particle coordinate )
- **FFT** ( charge density function )
- **PoissonSolver** ( Furies coefficients )
- **E\_SC** ( electric field potentials )



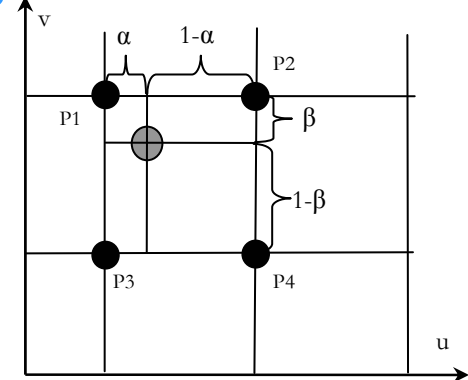


# \_\_global\_\_ void Track ()

- Function with many parameters. Use variable type `__constant__` :
  - `__device__ __constant__ float d_float[200];`
  - `__device__ __constant__ int d_int[80];`
- Particle number corresponds:
  - `int n = threadIdx.x+blockIdx.x*blockDim.x;`
- Number of “if, goto, for” should be decreased
- Linear interpolation field maps
  - `texture < float, 2, cudaReadModeElementType > Ex_TexRef;`
  - `Ex_TexRef.filterMode = cudaFilterModeLinear;`

$$P = [(1-\alpha)P1 + \alpha P2](1-\beta) + [(1-\alpha)P3 + \alpha P4]\beta$$

$$0 \leq \alpha, \beta \leq 1$$





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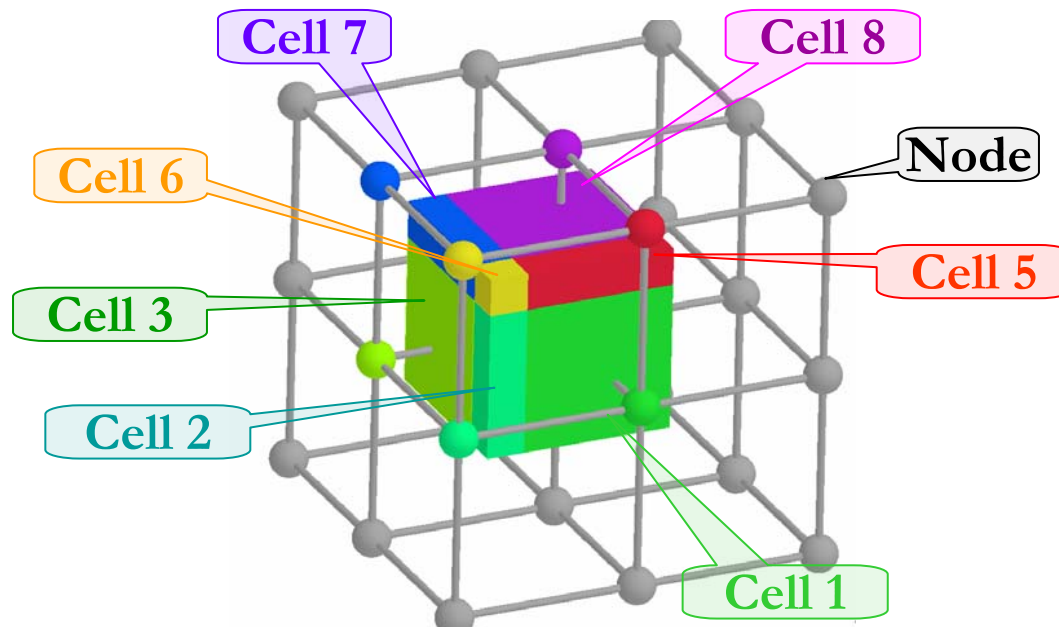
## \_\_global\_\_ void Losses ()

- Geometry structure consist of triangles.
- Block threads copies the triangle nodes from **global** to **shared** memory.
- Threads synchronize after copy operation **\_\_syncthreads()**
- Particle number corresponds to thread number:
  - **int n = threadIdx.x+blockIdx.x\*blockDim.x;**
- Check particles and triangles match



# \_\_global\_\_ void Rho

- Calculate charge impact in nodes of the mesh from particle with number  $n = \text{threadIdx.x} + \text{blockIdx.x} * \text{blockDim.x}$
- Particle gives impact to 8 nodes. Therefore, each thread store 16 values: 8 – numbers of node and 8 – values of charge density.
- For each node summarize all impacts of charge density.





# \_\_global\_\_ FFT ( )

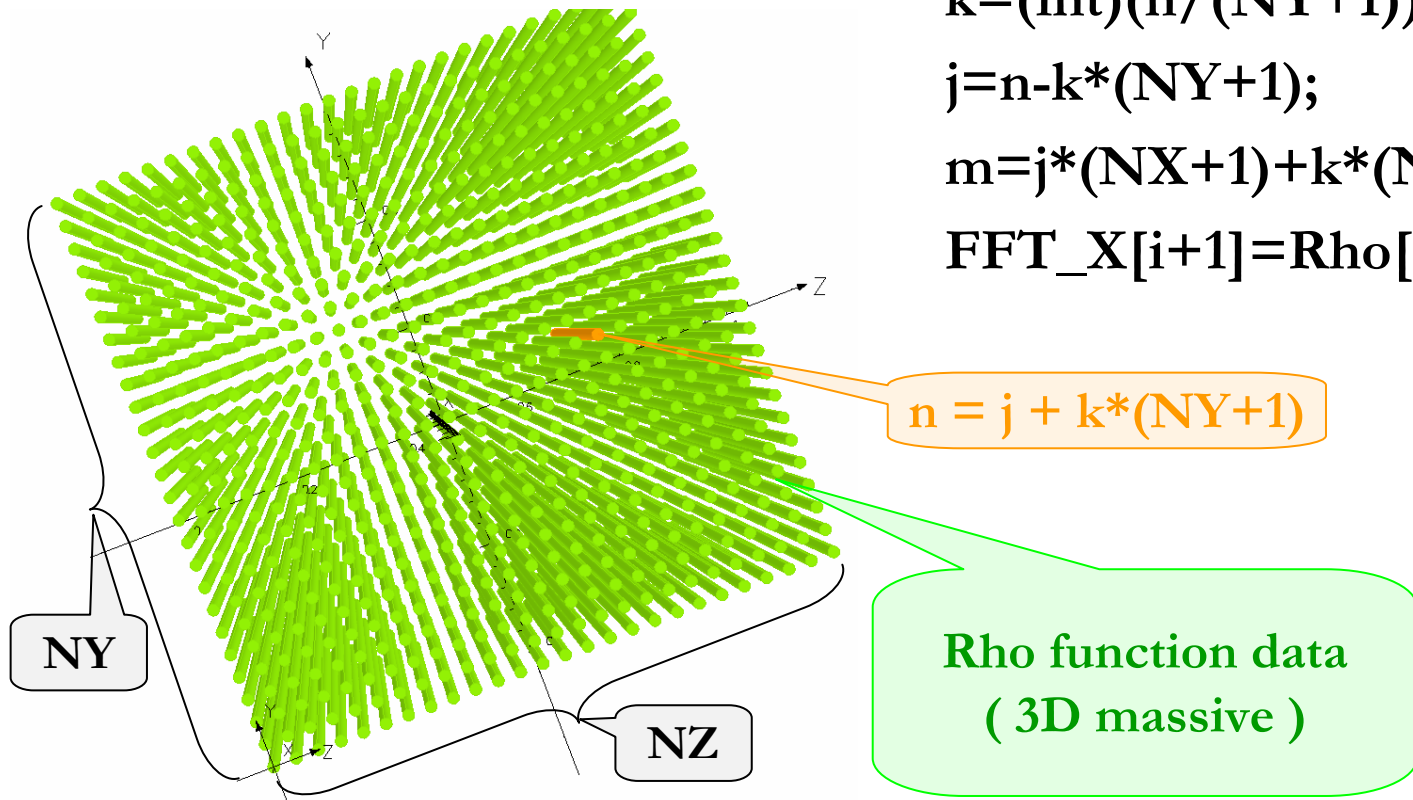
- Used real FFT for  $\sin(\pi n/N)$  basis function
- 3D transform consist of three 1D FFT for each axes: X, Y, Z
- `int n = threadIdx.x+blockIdx.x*blockDim.x;`

```
k=(int)(n/(NY+1));
```

```
j=n-k*(NY+1);
```

```
m=j*(NX+1)+k*(NX+1)*(NY+1);
```

```
FFT_X[i+1]=Rho[i+m];
```



$n = j + k \cdot (NY + 1)$

Rho function data  
( 3D massive )



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# \_\_global\_\_ PoissonSolver ()

- Thread number

```
int n = threadIdx.x+blockIdx.x*blockDim.x;
```

- Each thread calculate Fourier coefficient PhiF of potential function Phi

$$\text{PhiF}_{\text{ind}(i,j,k)} = -\text{RhoF}_{\text{ind}(i,j,k)} / (kx_i^2 + ky_j^2 + kz_k^2)$$

in the node:

$$\text{ind}(i,j,k) = i + j * (\text{NX} + 1) + k * (\text{NX} + 1) * (\text{NY} + 1),$$

where

$$k = (\text{int})(n / ((\text{NX} + 1) * (\text{NY} + 1)));$$

$$j = (\text{int})(n - k * ((\text{NX} + 1) * (\text{NY} + 1)) / (\text{NX} + 1));$$

$$i = n - j * (\text{NX} + 1) - k * ((\text{NX} + 1) * (\text{NY} + 1));$$

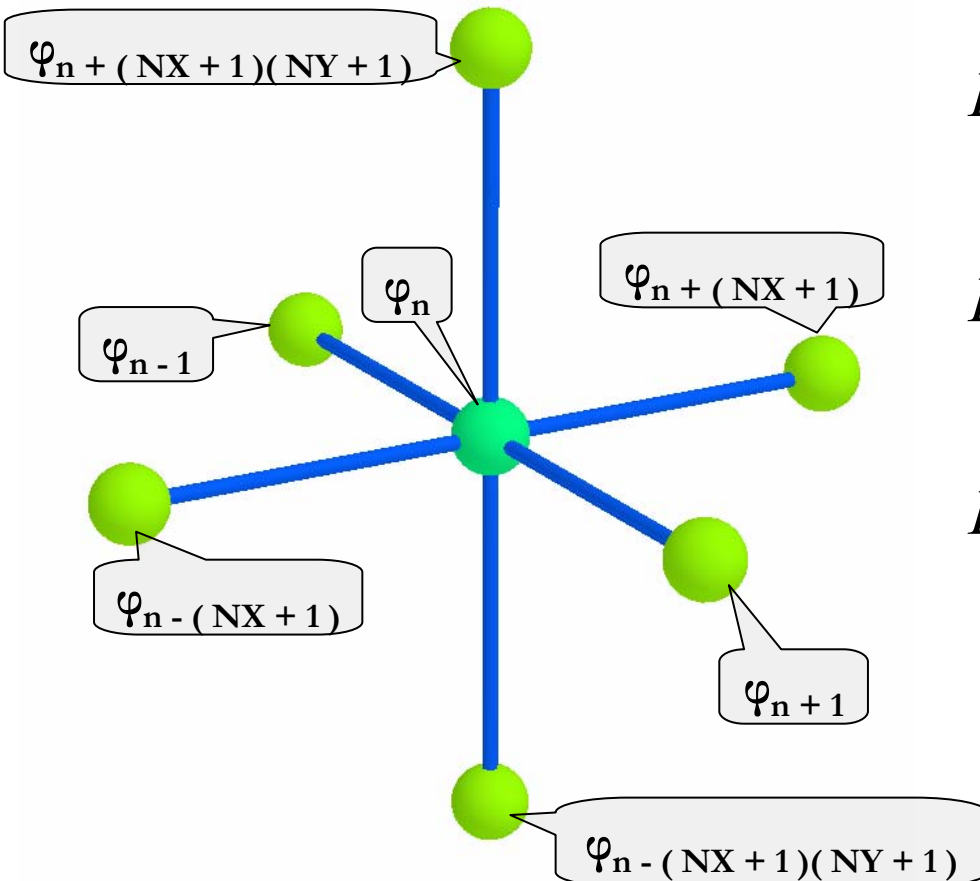
- RhoF – Fourier coefficients of charge density function Rho.



# \_\_global\_\_ E\_SC ()

- Electric field calculation at mesh node

```
int n = threadIdx.x+blockIdx.x*blockDim.x+startInd
```



$$E_x = -\frac{\varphi_{n+1} - \varphi_{n-1}}{2h_x}$$

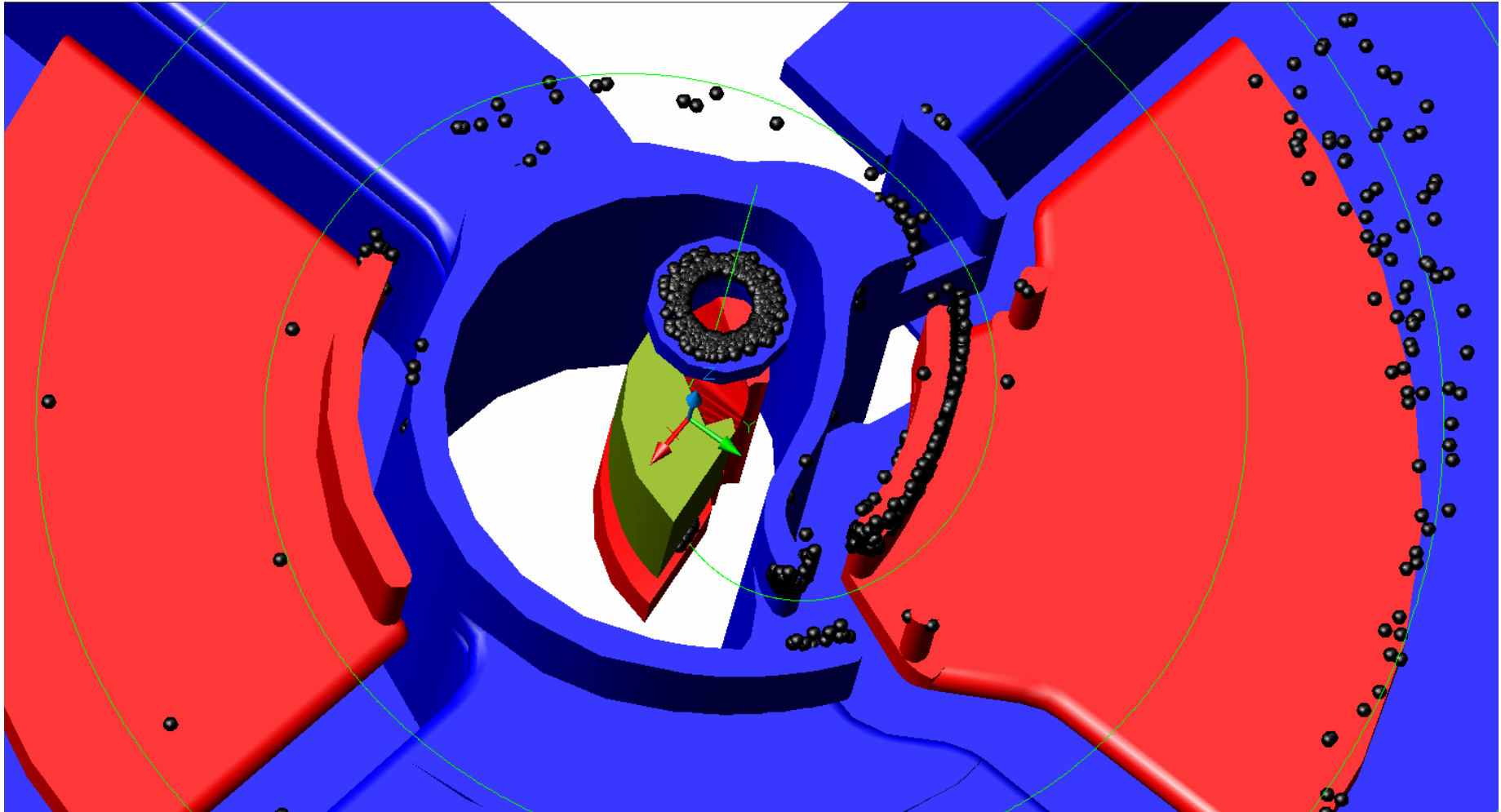
$$E_y = -\frac{\varphi_{n+(Nx+1)} - \varphi_{n-(Nx+1)}}{2h_y}$$

$$E_z = -\frac{\varphi_{n+(Nx+1)(Ny+1)} - \varphi_{n-(Nx+1)(Ny+1)}}{2h_z}$$



# Particle losses

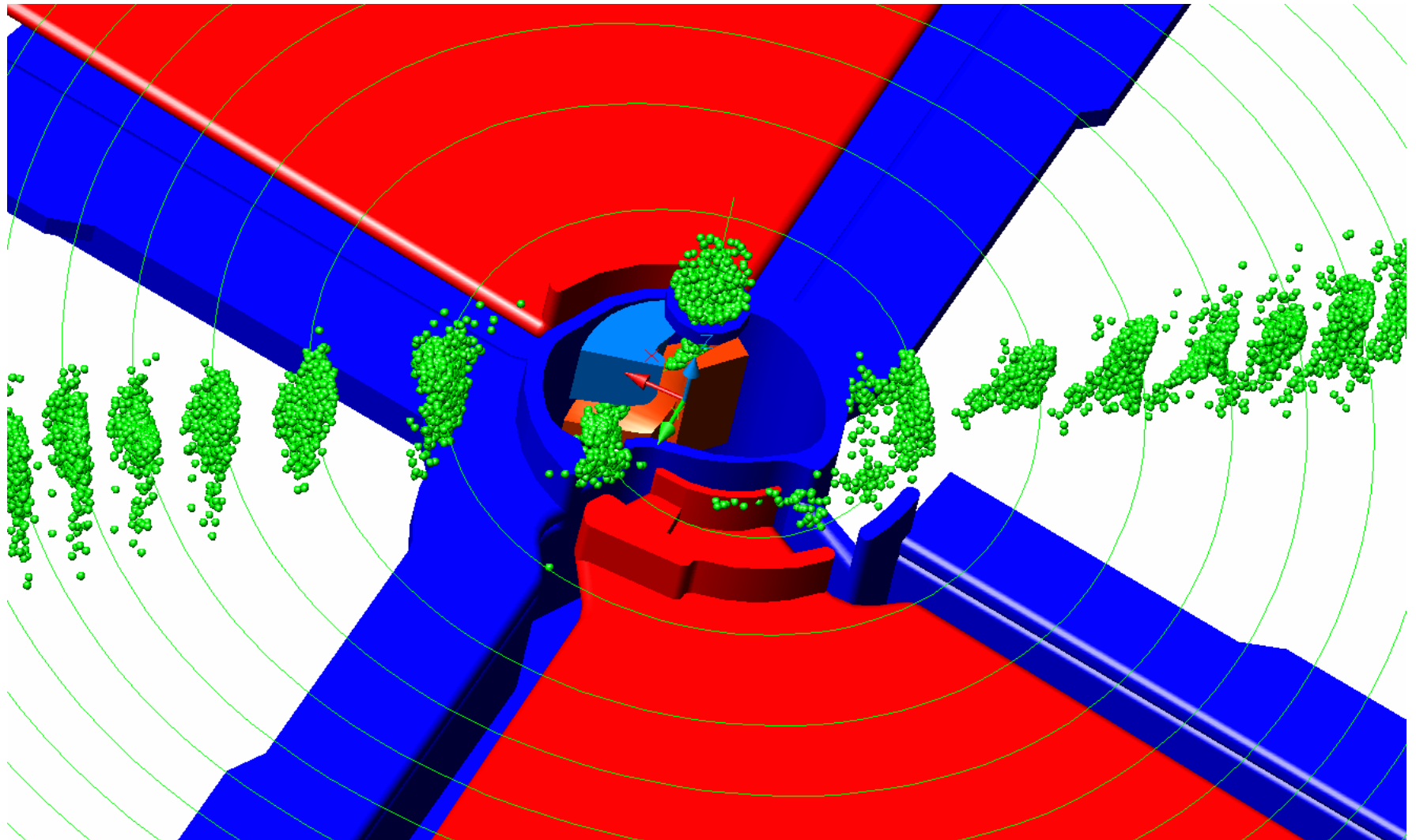
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# Bunch acceleration

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# GeForce 8800GTX

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CUDA kernel-function*	Time, [ms]		Rate, [x]
	CPU**	GPU	
Track	486	30	16
Losses	6997	75	93
Rho	79	6	14
Poisson/FFT	35	3	13
E_SC	1.2	0.8	1.4
Total	7598	114	67

\*Mesh size:  $2^5 \times 2^5 \times 2^5$ . Number of particles: 100,000 triangles: 2054

\*\*CPU 2.4 GHz



# GeForce 8800GTX

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Number of particles	Time calculation		Rate, [x]
	CPU*	GPU	
1,000	3 min. 19 sec.	12 sec.	17
10,000	34 min. 14 sec.	42 sec.	49
100,000	5 h. 41 min.	6 min.	56
1,000,000	2 days 8 h. 53 min.	1 h.	60

\*CPU 2.4 GHz



# Tesla C1060

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Number of particles	Time calculation		Rate, [x]
	CPU 2.5GHz	GPU C 1060	
1,000	3 min. 12 sec.	11 sec.	18
10,000	32 min. 24 sec.	27 sec.	72
100,000	5 h. 14 min. 31 sec.	3 min. 34 sec.	88
1,000,000	2 days 4 h. 25 min.	34 min. 29 sec.	91

without space charge effect



# Tesla C1060

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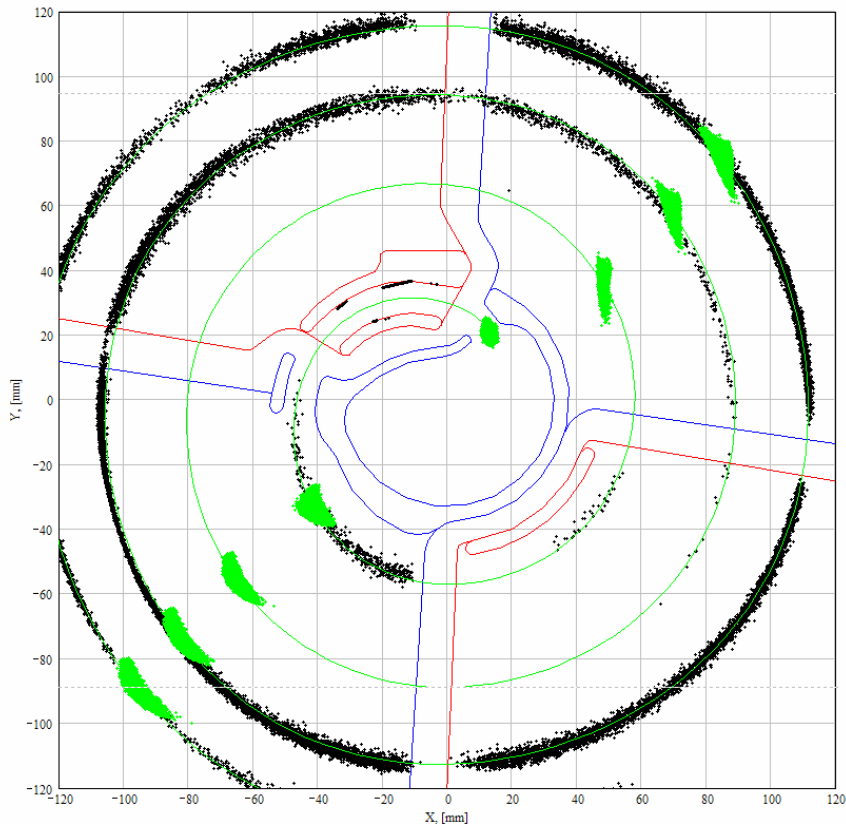
Number of particles	Time calculation		Rate, [x]
	CPU 2.5 GHz	GPU C 1060	
10,000	33 min. 36 sec.	44 sec.	45
100,000	5 h. 28 min. 12 sec.	5 min. 4 sec.	65
1,000,000	2 days 8 h. 27 min.	50 min. 17 sec.	67

with space charge effect

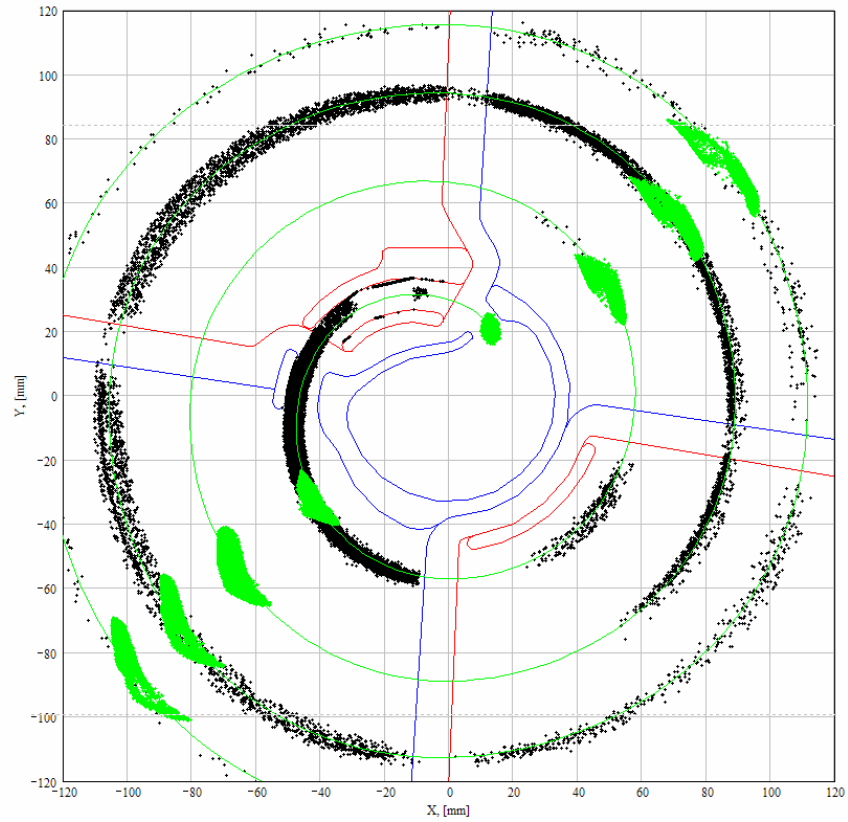


# Space charge effect

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$I \sim 0$   
Losses 24%



$I = 4 \text{ mA}$   
Losses 94%



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# Conclusions

- **Inexpensive technology.**
- **Increased performance 60-90 times gives a chance to perform the whole cyclotron computer modeling.**
- **Very careful programming is required that is the price for the obtained high performance of calculations.**
- **Application to other complicated simulation, related to the accelerator physics (beam halo etc), is possible.**



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